

Distribution Properties of Gauss Hypergeometric Function of Matrix Variable

Dr. Yogesh Sharma
Department of Mathematics
Jodhpur National University
Jodhpur

Abstract:- In this paper we establish distribution properties involving gauss hypergeometric function and finding moment generating function, r^{th} moment about origin, mean, variance, mellian, and laplace transform have been worked out. The argument and parameter are restricted to take only those values for which the density functions are non negative and have meaning. All the matrices considered are real positive, definite and symmetric matrices of order $p \times p$.

2010 Mathematics Subject Classification: 44A10, 44A35, 15XX, 26A33

Key words: Laplacetransform, integral equation, matrix argument

1. INTRODUCTION

LAPLACE AND INVERSE LAPLACE TRANSFORMS

Laplace and inverse Laplace transforms of matrices argument are respectively given by equations

$$(1.1) \quad L_T[f(Z)] = \int_{T>0} e^{tr(-TZ)} f(T) dT = \Phi(Z)$$

And

$$(1.2) \quad \frac{2^{p(p-1)/2}}{(2\pi i)^{p(p+1)/2}} \int_{\text{Re}(Z)>0} e^{tr(TZ)} \Phi(Z) dZ = \begin{cases} f(T), T > 0 \\ 0, \text{elsewhere} \end{cases}$$

Where $\Phi(Z)$ is complex analytic function and integral is taken over $Z=X+i Y$ with fixed $X > X_0$ and Y over the space S_p^* . For the conditions and details the readers see to Mathai [2],[3] Mathai and saxena[1], Seemon Thomas, Alex Thannippara and Mathai[4] Sharma [6] obtain the solution of the integral equation of matrix argument and generalized stieljtjes transform of matrix argument.

2. Main results

Theorem1:

$$I = \int_{X>0} \text{etr}(-BX) |X|^{\alpha - \frac{(p+1)}{2}} \phi(X) dX$$

If we take,

$$\begin{aligned} \phi(X) &= \frac{\Gamma_p(\gamma + \nu + \frac{(p+1)}{2})}{\Gamma_p(\nu + \frac{(p+1)}{2})} {}_2F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}; \nu + \frac{p+1}{2}; -RX) \\ &= P_\gamma^{\nu, \delta}(X) \end{aligned}$$

given integral reduce to

$$(2.1) \quad I = |B|^{-\alpha} \frac{\Gamma_p(\gamma + \nu + \frac{(p+1)}{2}) \Gamma_p(\alpha)}{\Gamma_p(\nu + \frac{(p+1)}{2})} {}_3F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}; \alpha; \nu + \frac{p+1}{2}; -RB^{-1})$$

thus the Function

$$(2.2) \quad f(X) = \frac{|X|^{\alpha - \frac{(p+1)}{2}} \text{etr}(-BX) {}_2F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}; \nu + \frac{p+1}{2}; -RX)}{\Gamma_p(\alpha) |B|^{-\alpha} {}_3F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}; \alpha; \nu + \frac{p+1}{2}; -RB^{-1})}$$

$$\begin{aligned} \text{where } \text{Re}(\alpha) &> \frac{p-1}{2} \\ &= 0, \text{ elsewhere} \end{aligned}$$

gives a probability density function (p.d.f).

Special Cases: If we put R=I, the identity matrix of order p and B→0, and using result given by as Mathai and Saxena[1, 5.2.35], we get

$$(2.3) \quad \int_{X>0} |X|^{\alpha - \frac{(p+1)}{2}} \frac{\Gamma_p(\gamma + \nu + \frac{(p+1)}{2})}{\Gamma_p(\nu + \frac{(p+1)}{2})} {}_2F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}; \nu + \frac{p+1}{2}; -RX)$$

$$= \frac{\Gamma_p(\gamma + \nu + \frac{(p+1)}{2}) \Gamma_p(\alpha) \Gamma_p(\nu + \delta + \gamma + \frac{p+1}{2} - \alpha) \Gamma_p(-\gamma - \alpha)}{\Gamma_p(\nu + \frac{(p+1)}{2} - \alpha) \Gamma_p(\nu + \delta + \gamma + \frac{p+1}{2}) \Gamma_p(-\gamma)}$$

$$\begin{aligned} \text{where } \text{Re}(\alpha) &> \frac{p+1}{2}, \text{Re}(\gamma + \nu + \frac{(p+1)}{2}) > \frac{p-1}{2}, \text{Re}(\alpha) > \frac{p-1}{2}, \text{Re}(\nu + \frac{(p+1)}{2}) > \frac{p-1}{2} \\ &= 0, \text{ elsewhere} \end{aligned}$$

Characteristic Function

The characteristic function $\phi_X(T)$ of X is given by

$$(2.4) \quad \phi_X(T) = E[\exp\{itr(XT)\}] \\ = \int_{X>0} \exp\{itr(XT)\}f(X)dX$$

where $i = (-1)^{\frac{1}{2}}$, T is $p \times p$ symmetric matrix of characteristic function variables and E denotes mathematical expectation.

by virtue of (2.4), we get characteristic function as

$$(2.5) \quad \phi_X(T) = \frac{|B - iT|^{-\alpha} {}_3F_1[-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}; \alpha; \nu + \frac{p+1}{2}; -R(B - iT)^{-1}]}{|B|^{-\alpha} {}_3F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}; \alpha; \nu + \frac{p+1}{2}; -RB^{-1})}$$

where $\text{Re}(\alpha) > \frac{p+1}{2}$, $\text{Re}(\gamma + \nu + \frac{(p+1)}{2}) > \frac{p-1}{2}$, $\text{Re } B > O$, $\text{Re}(B) > O$
=0, elsewhere ...

Moment Generating Function (m.g.f)

$$(2.6) \quad E[etr(XT)] = \int_{X>0} \exp\{tr(XT)\}f(X)dX$$

By virtue of (2.2), we get characteristic function as

$$E[etr(XT)] = \frac{|B - T|^{-\alpha} {}_3F_1[-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}; \alpha; \nu + \frac{p+1}{2}; -R(B - T)^{-1}]}{|B|^{-\alpha} {}_3F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}; \alpha; \nu + \frac{p+1}{2}; -RB^{-1})}$$

where (2.7) $\text{Re}(\alpha) > \frac{p+1}{2}$, $\text{Re}(\gamma + \nu + \frac{(p+1)}{2}) > \frac{p-1}{2}$, $\text{Re } B > O$, $\text{Re}(B) > \text{Re}(R)$
=0, elsewhere

r^{th} Moment of the Distribution

The r^{th} moment about origin of the matrix variable X with p.d.f (2.2) is given by

$$(2.8) \quad E[|X|^r] = \int_{X>0} |X|^r f(X)dX$$

$$E[|X|^r] = \frac{|B|^{-r} {}_3F_1[-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}; \alpha + r; \nu + \frac{p+1}{2}; -RB^{-1}]}{{}_3F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}; \alpha; \nu + \frac{p+1}{2}; -RB^{-1})}$$

where $\text{Re}(\alpha) > \frac{p+1}{2}$, $\text{Re}(\gamma + \nu + \delta + \frac{(p+1)}{2}) > \frac{p-1}{2}$, $\text{Re } B > O$
=0, elsewhere

Mean and Variance of the distribution

$$E[|X|^1] = \int_{X>0} |X|^1 f(X)dX$$

$$(2.9) E[|X|^1] = \frac{|B|^{-1} {}_3F_1[-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}, \alpha + 1; \nu + \frac{p+1}{2}; -RB^{-1}]}{{}_3F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}, \alpha; \nu + \frac{p+1}{2}; -RB^{-1})}$$

and

$$E[|X|^2] = \frac{|B|^{-1} {}_3F_1[-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}, \alpha + 2; \nu + \frac{p+1}{2}; -RB^{-1}]}{{}_3F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}, \alpha; \nu + \frac{p+1}{2}; -RB^{-1})}$$

by definition, variance = $E(|X|^2) - [E(|X|)]^2$, we get

Variance =

(2.10)

$$\frac{|B|^{-2} \{[{}_3F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}; \alpha + 2; \nu + \frac{p+1}{2}; RB^{-1}) - {}_3F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}, \alpha + 1; \nu + \frac{p+1}{2}; -RB^{-1})\}}{[{}_3F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}, \alpha; \nu + \frac{p+1}{2}; -RB^{-1})]^2}$$

$$\operatorname{Re}(\alpha) > \frac{p-1}{2}$$

Mellian and Laplace Transform of the Distribution

by definition of mellian transform is

$$(2.11) M[f(X)] = \int_{X>0} |X|^{\delta - \frac{(p+1)}{2}} f(X) dX$$

$$= \frac{|B|^{-\delta + \frac{p+1}{2}} {}_3F_1[-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}, \alpha + \delta + \frac{p+1}{2}; \nu + \frac{p+1}{2}; -RB^{-1}]}{{}_3F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}, \alpha; \nu + \frac{p+1}{2}; -RB^{-1})}$$

By definition of Laplace transform is

$$(2.12) L[f(X)] = \int_{X>0} e^{-TX} f(X) dX$$

$$= \frac{|B+T|^{-\alpha} {}_3F_1[-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}, \alpha; \nu + \frac{p+1}{2}; -R(B+T)^{-1}]}{|B|^{-\alpha} {}_3F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}, \alpha; \nu + \frac{p+1}{2}; -RB^{-1})}$$

where $\operatorname{Re}(\alpha) > \frac{p+1}{2}$, $\operatorname{Re}(\gamma + \nu + \frac{(p+1)}{2}) > \frac{p-1}{2}$, $\operatorname{Re} B > O$, $\operatorname{Re}(B) > O$
= 0, elsewhere .

Particular Cases: if we take Matrix of order 1×1 i.e if we take $p=1$ we and $B=1$, given matrix reduce to scalar variable i.e

$$f(x) = \frac{|x|^{\alpha - \frac{(p+1)}{2}} \text{etr}(-bx) {}_2F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}; \nu + \frac{p+1}{2}; -rx)}{\Gamma_p(\alpha) |b|^{-\alpha} {}_3F_1(-\gamma, \nu + \delta + \gamma + \frac{p+1}{2}; \alpha; \nu + \frac{p+1}{2}; -rb^{-1})}$$

$$, \text{Re}(\alpha) > \frac{p+1}{2}, \text{Re}(\gamma + \nu + \frac{(p+1)}{2}) > \frac{p-1}{2}$$

REFERENCES

1. Mathai.A.M and saxena R.K: **The H –function with Applications in Statistics and Other disciplines**, john –Wiley & sons, new York(1978)
2. Mathai.A.M: **Jacobians of Matrix Transformations and Function of Matrix Argument**; world scientific publishing co pte ltd; Singapore.(1997)
3. Mathai A.M. : **Fractional integrals in the Matrix-Variate cases and connection to statistical distributions. *Integral Transforms and Special Functions*, 20(12),871-882 (2009).**
4. Seemon Thomas, Alex Thannippara and A.M. Mathai :**on a matrix-variate generalized type -1 Dirichlet model, *Journal of Probability and Statistical Science*, 6(2), 187-200 (2008).**
5. Sharma Yogesh: **Generalized Stieltjes Transform of Matrix Variable**;, Indian Academy of Mathematics, vol27(2)(2005)289-293.